

Others : Paper (1/1)

Project : *Paper Handling Robot System*

- Client : Yuhan-Kimberly
- Basic Specification
 - Workpiece : Paper
 - Position Repeatability : ± 0.5 mm
 - Cycle Time : 7.5 Sec/Box
 - Max. Payload : 100 Kgf
- Major Components
 - Robot : 1 Set
 - Robot Hand
 - Pallet Conveyer System
 - Control System

