

## Others : Paper (1/1)

### Project : *Paper Handling Robot System*

- Client : Paper Company
- Basic Specification
  - Workpiece : Paper
  - Position Repeatability :  $\pm 0.5$  mm
  - Cycle Time : 7.5 Sec/Box
  - Max. Payload : 100 Kgf
- Major Components
  - Robot : 1 Set
  - Robot Hand
  - Pallet Conveyer System
  - Control System

